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## Unsupervised Learning

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## Quick Question!

[^0]
## Content

- But what is Unsupervised Learning?
* Recap of Linear Regression
* Some Unsupervised Learning methods
- Latent Variable Models
- Singular Value Decomposition (SVD)
- Principle Component Analysis (PCA)
- Autoencoders
- t-SNE (visualization)
- Variational Inference
- Clustering
- K-means
- Food for thought


## But what is Unsupervised Learning?

-Generally, predictive ML tasks look like this- given a set of $\left\{\right.$ data, targets $_{i} i \in\{1, n\}$ we need to predict the target for the $\{\text { new data }\}_{n+1}$

* However for unsupervised learning tasks, we do not have any targets provided to us!
* So the challenging task is to infer the targets, with the data itself. Hence, we are essentially concerned with learning patterns from our data.
* Broad categories in unsupervised learning:
- Clustering
- Anomaly detection
- Latent Variable Models


## Recap of Linear regression

$$
\begin{gathered}
y_{1}=\beta_{0}+\beta_{1} x_{1}+\epsilon \\
y_{2}=\beta_{0}+\beta_{1} x_{2}+\epsilon \\
\vdots \\
y_{n}=\beta_{0}+\beta_{1} x_{n}+\epsilon
\end{gathered}
$$

$$
y_{i}=\beta_{0}+\beta_{1} x_{i}+\epsilon \text { for } i \in\{1, n\}
$$

* Least square estimates


$$
\boldsymbol{b}=\left[\begin{array}{c}
b_{1} \\
b_{2} \\
\vdots \\
b_{k}
\end{array}\right]=\left(\boldsymbol{X}^{T} \boldsymbol{X}\right)^{-1} \boldsymbol{X}^{T} \boldsymbol{Y}
$$

* Problems with Multicollinearity $\left(\boldsymbol{X}^{T} \boldsymbol{X}\right)^{-1}$ in $\boldsymbol{b}$ cannot be calculated if the columns of $\boldsymbol{X}$ are linearly dependent


## Singular Value Decomposition

*SVD of a real or complex matrix $A \in R^{m \times n}$ has three main steps:

* Rotation
* Followed by rescaling

$$
A=U \Sigma V^{T}
$$

* Followed by another rotation

* It generalizes the eigen decomposition of a square normal matrix with an orthonormal eigen basis to any $m \times n$ matrix.

```
m\geqn with rank(A)=nas large as possible
```


## $U \in R^{m \times m}$ is matrix of orthonormal eigenvectors of $A A^{T}$ <br> $V \in R^{m \times m}$ is matrix of orthonormal <br> eigenvectors of $A^{T} A$ <br> $\Sigma \in R^{r \times r}$ is a diagonal matrix with elements equal to the root of the positive eigenvalues of $A A^{\mathrm{T}}$





## Singular Value Decomposition: Application

$$
A=U \Sigma V^{T}
$$

Each entry of matrix represents a pixel value
*Think now about $\boldsymbol{A}$ as containing the grayscale values of a black-and-white image
*SVD of the baboon represents the baboon image as a superposition of 512 simple images, each one only showing horizontal/vertical stripes.

```
baboon.svd <- svd(bab) # May take some time
baboon.1 <- sweep(baboon.svd$u[, 1, drop=FALSE], 2,
        baboon.svd$d[1], "*") %*%
            t(baboon.svd$v[, 1, drop=FALSE])
baboon.20 <- sweep(baboon.svd$u[, 1:20, drop=FALSE], 2,
    baboon.svd$d[1:20], "*") %*%
    t(baboon.svd$v[ , 1:20, drop=FALSE])
```



Low rank decomposition of the
image with 1 and 20 components

* Let us finally look at the "residual image", the image reconstructed from the 20 rank-one images with the lowest singular values.


## Principle Component Analysis

- A special case of SVD (applied on the $\boldsymbol{X}$ matrix)!
*Principal components account for the variance in the data set amongst different axes.
* Purple line: the line that maximizes the variance. (also the first component)
* The second principal component is calculated in the same way, with the condition that it is uncorrelated with (i.e., perpendicular to) the first principal component and that it accounts for the next highest variance.




## Autoencoders

* A type of neural network used to learn efficient latent representations of unlabeled data by forcing the data to be pushed into a lower dimension.
*An autoencoder learns two functions: an encoding function that transforms the input data, and a decoding function that recreates the input data from the encoded representation.
\%Finally, the loss between the input and the output is minimized.
*This forces the encoding function to learn only the most important features from the data which will help it reconstruct it back.



## t-distributed Stochastic Neighbour Embedding (t-SNE)

- $\boldsymbol{A} \mid$ Points: $7344 \mid$ Dimension: 6
(3)



## K-means clustering

*Iterative process where we minimize the distance of the data point wss from the average data point in the cluster.

* Distance Measures:
- Euclidian
- Manhattan
- Cosine

$$
W S S=\sum_{i=1}^{m}\left(x_{i}-c_{i}\right)^{2}
$$



No. of clusters

For each value of $k$. The value of $k$, which has the largest change in amount of WSS, is taken as the optimum value.


## Variational Inference

* A OP technique to learn probability distributions (which are often nasty or not expressible in closed form).

Example: Suppose $Z \sim \mathcal{N}\left(\mu, \sigma^{2}\right)$ and $Y \sim$ Pois $\left(e^{z}\right)$ How can we infer $\mu, \sigma$ given only $Y$ ?

* Approach: Approximate your target distribution using a simpler but more accurate distribution.
- Measure of dissimilarity: KL divergence. This reduces the sampling problem to an optimization problem!




## Food for thought

Q. Which of the following techniques would perform better for reducing the dimensions of a data set?
A. Removing columns that have too many missing values
B. Removing columns that have high variance in data
C. Removing columns with dissimilar data trends
D. None of these

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C. Reduction in the dimensions of the original image
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## Customer Churn Prediction (Demo Project)

Repo:
https://github.com/A
nanyapam7/Custome
r-Churn-
Prediction?tab=read me-ov-file
Feel free to star it ;)


R HTML Page:
https://students.iis erkol.ac.in/~ad18m s075/notebooks/n otebook-eda.html

## Thank you!

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- Computer Age Statistical Inference -T. Hastie

In case you want to discuss further, feel free to connect me on any of these platforms:)
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This is me :-)



[^0]:    * Suppose you have a nice square matrix $\boldsymbol{A}$ and a randomly sampled vector $\boldsymbol{v}$ from the space.
    * Now suppose you kept transforming your vector $\boldsymbol{v}$ by $\boldsymbol{A}$ for quite a number of times, i.e. you compute $\boldsymbol{A v}, \boldsymbol{A}(\boldsymbol{A v}), \boldsymbol{A}(\boldsymbol{A}(\boldsymbol{A v})), \ldots$ and so on until you are tired.

    Where do you think your vector will finally land up?

